# Optimization Project in Energy ENT306

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**2** ON/OFF devices



#### Indices

Set of dams I

#### Optimization variables

- $q_{i,t}$ : water level of dam *i* at the beginning of time interval  $t \in \{1, ..., T + 1\}$
- $x_{i,t}$ : amount of water exploited at dam *i* during time interval  $t \in \{1, ..., T\}$
- $y_{(i,j),t}$ : amount of water transported over the river (i,j) during the time interval  $t \in \{1, ..., T\}$
- $z_{i,t}$ : amount of water exploited at dam *i* during the time interval  $t \in \{1, ..., T\}$ , not transported to any other dam.

## Hydro valley

#### Parameters

- $P_{i,t}$ : precipitation at *i*, during the time interval *t*
- *Q<sub>i</sub>*: storage capacity of dam *i*
- K<sub>i</sub>: initial level of dam i
- $D_t$ : electricity demand during the time interval t

### Functions

- *f<sub>i</sub>*: *x* → *f<sub>i</sub>(x)*: exploitation cost on a given time interval at dam *i*, as a function of the amount of exploited water *x*.
- g<sub>i</sub>: x → g<sub>i</sub>(x): electricity production as a function of the amount of exploited water at dam i.

#### **Cost function**

$$\min_{q,x,y,z} \sum_{t=1}^{T} \sum_{i \in I} f_i(x_{i,t}).$$

#### Constraints

Nonnegativity of the variables:

$$q_{i,t} \geq 0, \quad x_{i,t} \geq 0, \quad y_{(i,j),t} \geq 0, \quad z_{i,t} \geq 0.$$

Bounds:

$$q_{i,t} \leq Q_i, \quad \forall t \in \{1,...,T+1\}.$$

Initial condition:

$$q_{1,i}=K_i.$$

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Demand satisfaction:

$$\sum_{i\in\mathcal{I}}g_i(x_{i,t})=D_t,\quad\forall t\in\{1,...,T\}.$$

• Evolution of the water level in each dam:

$$q_{i,t+1} = q_{i,t} + P_{i,t} - x_{i,t} + \sum_{\substack{j \in \mathcal{I} \\ (j,i) \in \mathcal{E}}} y_{(j,i),t}, \quad \forall t \in \{1, ..., T\}.$$

Amount of exploited water:

$$x_{i,t} = \sum_{\substack{j \in \mathcal{I} \\ (i,j) \in \mathcal{I}}} y_{(i,j),t} + z_{i,t}, \quad \forall t \in \{1, ..., T\}.$$

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### Hydro valley

### Dynamic programming.

We parametrize the problem by

- the initial time interval t
- the initial level of water in every dam  $q \in \mathbb{R}^{\mathcal{I}}$ .

Let V(t,q) denote the corresponding optimal cost.

We have V(T + 1, q) = 0.

#### Dynamic programming principle

Let  $t \in \{1, ..., T\}$  and let  $q \in \prod_{i \in \mathcal{I}} [0, Q_i]$ . Then

$$V(t,q) = \inf_{\substack{q' \in \mathbb{R}^{\mathcal{I}}, x \in \mathbb{R}^{\mathcal{I}}, \\ y \in \mathbb{R}^{\mathcal{E}}, z \in \mathbb{R}^{\mathcal{I}}}} \left( \sum_{i \in \mathcal{I}} f_i(x_i) \right) + V(t+1,q'), \qquad (DP(t,q))$$

subject to:

- Non-negativity:  $q'_i \ge 0$ ,  $x_i \ge 0$ ,  $y_{(i,j)} \ge 0$ ,  $z_i \ge 0$ .
- Bounds:  $q'_i \leq Q_i$ .
- Demand:  $\sum_{i\in\mathcal{I}}g_i(x_i)=D_t$ .
- Conservation:  $q'_i = q_i + P_{i,t} x_i + \sum_{\substack{j \in \mathcal{I} \\ (i,i) \in \mathcal{E}}} y_{(j,i)}$ .

• Exploitation : 
$$x_i = \sum_{\substack{j \in \mathcal{I} \\ (i,j) \in \mathcal{I}}} y_{(i,j)} + z_i.$$

Remarks.

Why does it work?

 $\rightarrow$  The level of water in the dams at time *t* is a **sufficient information** to take optimal decisions from *t* until the end of the optimization process.

 $\rightarrow$  Knowing the level of water in the dams at time *t*, one can completely **forget** what happened in the past.

- The dynamic programming principle characterizes globally optimal solutions, even if the original problem is non convex.
- In the practical implementation of the method, one needs to discretize the variable q. The number of discretization points grows exponentially with the number of dams. This phenomenon is called curse of dimensionality.

2 ON/OFF devices



# ON/OFF devices

### Context:

- Set of {1,...,*I*} production units (e.g. nuclear power plants).
- These plants can be put into standby and reactived after some time, at some time to be optimized.

### Constraints on disactivation and activation (unit *i*):

- Maximal activity duration:  $X_i^{\text{on}}$  days.
- Minimal standby duration: X<sub>i</sub><sup>off</sup> days.

#### Decision variables on time interval t, associated with unit i:

- Production  $u_i(t)$  (if *i* is activated).
- Activation/Disactivation/No change.

# ON/OFF devices

#### States set:

The set  $X_i$  describes of possible states of the unit *i*. It is defined by

$$\mathcal{X}_i = \{(0, x) \,|\, x = 0, ..., X_i^{off}\} \cup \{(1, x) \,|\, x = 0, ..., X_i^{on}\}.$$

Interpretation:

- (0, x) : unit *i* has been OFF for x days,
- (1, x): unit *i* has been ON for x days.

If the unit *i* has been OFF for strictly more that  $X_i^{\text{off}}$ , the state is represented by  $(0, X_i^{\text{off}})$ .

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# ON/OFF devices

#### **Transitions:**

We denote  $\mathcal{E}_i \subset \mathcal{X}_i \times \mathcal{X}_i$  the set of possible transitions from one state to the other. We have

Transition e		Coût $f(e)$
$(1,x) \rightarrow (1,x+1),$	$x = 0,, X_i^{on} - 1$	0
(1,x)  ightarrow (0,0),	$x = 0,, X_i^{on} - 1$	0
$(0,x) \rightarrow (0,x+1),$	$x = 0,, X_i^{off} - 1$	0
$(0, X_i^{\mathrm{off}}) \rightarrow (0, X_i^{\mathrm{off}})$		0
$(0, X_i^{off})  ightarrow (1, 0)$		$C_i > 0$

The only transition with non-zero cost is the one corresponding to the activation of unit i.

# ON/OFF devices

#### Other parameters:

- D(t): electricity demand on interval t
- $U_i$ : maximal production of unit *i* (if the unit is activated).

#### **Optimization variables:**

- x<sub>i</sub>(t) : state of the unit i at the beginning of the time interval
- $u_i(t)$ : production of unit *i* over the interval *t*.

**Production constraint:**  $(x_i(t), u_i(t)) \in C_i$ , where

$$\mathcal{C}_i := \big\{ ((0,x),0) \, | \, x = 1, ..., X_i^{\text{off}} \big\} \cup_{u \in [0,U_i]} \big\{ ((1,x),u) \, | \, x = 1, ..., X_i^{\text{on}} \big\}.$$

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# $\mathsf{ON}/\mathsf{OFF}$ devices

### Problem:

$$\min_{\substack{x_i(t), t=1,...,T+1\\u_i(t), t=1,...,t}} \sum_{t=1}^{T} \sum_{i=1}^{I} \ell_i(u_i(t)) + f_i(x_i(t), x_i(t+1)),$$
subject to:
$$\begin{cases} (x_i(t), u_i(t)) \in \mathcal{C}_i, \\ (x_i(t), x_i(t+1)) \in \mathcal{E}_i, \\ \sum_{i=1}^{I} u_i(t) = d(t), \\ x_i(1) = y_i. \end{cases}$$

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## ON/OFF devices

### Dynamic programming.

We parametrize the problem by

- initial state t
- state of the units  $x \in \prod \mathcal{X}_i$ .

Let V(t, x) denote the corresponding cost.

## ON/OFF devices

#### Dynamic programming principle

Let  $t \in \{1, ..., T\}$  and let  $x \in \prod X_i$ . It holds:

$$V(t,x) = \begin{cases} \inf_{\substack{x' \in \prod \mathcal{X}_i, \\ u \in \mathbb{R}^l}} \left( \sum_{i=1}^l \ell_i(u_i) + f_i(x_i, x_i') \right) + V(t+1, x') \\ \text{subject to:} \quad \begin{cases} (x_i, u_i) \in \mathcal{C}_i, \\ (x_i, x_i') \in \mathcal{E}_i. \\ \sum_{i=1}^l u_i = d. \end{cases} \end{cases}$$

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## ON/OFF devices

### Remarks.

- Originally a combinatorial problem.
- Curse of dimensionality.